

Reference to interpret ISO 10110 drawings (2023 Update) Full standard contains complete descriptions and explanations for proper use

David M. Aikens, Eric Herman, and Richard N. Youngworth

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Surface Form Tolerances and Evaluation^{5, 20}

- Units are preferred to be in nm, but allowed in μm or fringes
 - If fringes are the unit specified, a wavelength needs to be defined either in the title block or for the tolerance
- Written as 3/ A(B/C) PV(D) RMSx < E; λ = W
 - A = power: PV approximation spherical wavefront
 - When a dash is listed no tolerance applies otherwise a default power tolerance is present
 - B = irregularity: PV wavefront irregularity
 - C = rotationally invariant irregularity: PV rotational invariant irregularity
 - D = total deviation: PV total wavefront deviation
 - E = rms deviation; where x is
 - t = total rms surface deviation
 - i = rms surface deviation with power removed
 - a = asymmetric variant rms surface irregularity
 - W = wavelength (λ) in nm
 - If wavelength is not indicated in the title block, it must be specified in the tolerance
- Other than power, when a dash or nothing is listed in place of one of the tolerances, that type of tolerance will not be applied
- Further forms of surface form tolerances can be applied, such as surface slope or Zernike coefficients
 - Slope is written as 3/ $\Delta S_{v,w}(F/G/H)$
 - v = number of dimensions (1 or 2)
 - w = orientation
 - F = Max slope deviation (ξ)
 - G = sampling length
 - H = spatial sampling interval
 - Zernike coefficients written specifically as 3/ Z(n, m) (PV < O; RMS < P)
 - Z(n, m) = Zernike radial polynomial
 - O = PV surface form deviation
 - P = rms surface form deviation

Surface Texture⁸

- Polish code above the texture symbol is either P (polished), G (ground) or P1-P4 (polish grades) which indicate a default specification of surface texture
 - Polish grades are standardized surface roughness values over a spatial band of 0.002 mm to 1.00 mm
- Texture requirements written as follows
 - Each requirement on its own line, showing a spatial wavelength band and a surface texture specification separated by a /
 - Spatial wavelengths are given in mm
 - Rq indicates rms surface roughness in microns
 - Wq indicates rms surface waviness in microns
 - Sq indicates the areal rms surface texture in microns
 - RAq indicates rms surface slope in microradians
 - PSD indicates the maximum value of the power spectrum over the specified spatial wavelength band, given as a power coefficient and an intercept in $\text{nm}^2 \text{mm}$
- When upper and lower limits are provided they are indicated with a U or an L
- When the lay of the measurement is provided it is indicated as R (radial), C (circumferential), \perp (vertical) or = (horizontal).

Surface Centering Error Due to Tilt⁶

- Implicit datums exist for typical, centered, spherical elements. If datum features are unclear, one must be specified
- Written as follows:
 - Spherical Surface: 4/ σ
 - σ = maximum tilt relative to either the cylindrical surface (lens edge) or datum axis (optical axis)
 - Aspheric Surfaces or Rotationally Non-Variant Subassemblies: 4/ $\sigma(L)$
 - σ = maximum tilt
 - L = maximum lateral displacement
 - Beam deviation can be specified for the entire lens element: 14/ ρ
 - ρ = maximum transmitted beam deviation
 - Surface tilt can alternatively be specified by runout (e.g. lens edge measurement):
 - 4/a < A or 4/c < B
 - A = axial runout at the clear aperture
 - B = circular runout at the surface edge
- Tolerances can be applied as both angular and linear dimensions at single element or assembly level
- When a dash or nothing is listed in place of one of the tolerances, that type of tolerance will not be applied

Surface Imperfection Tolerances and Evaluation^{7, 21}

- Imperfections can be described by two methods
 - Visibility imperfections (MIL historical standard): 5/ S-D; CS'-D'; EA_e
 - Each group represents different types of imperfections
 - S-D = general surface scratch and dig designation
 - CS'-D' = coated aperture scratch and dig designation
 - EA_e = edge chips
 - A drawing note stating the make and model of the comparison standard to be used is necessary
 - Accumulation and concentration rules apply
 - Dimensional imperfections (DIN historical standard): N_g x A_g; CN_e x A_e; LN_i x A_i; EA_g
 - Each group with a different prefix designation classifies types of imperfections
 - No Prefix = general surface imperfections
 - C = coated aperture imperfection designation
 - L = long scratches outside of general surface grades
 - E = edge chips
 - Each designation is listed in two methods
 - N_g x A_g
 - N = Number of imperfections within a grade class
 - A = Grade class to characterize imperfections
 - Accumulation and concentration rules apply

Laser Damage Threshold^{17, 31, 32}

- Written as 6/ X_{th}; λ ; T_{th}
 - X can either be one of three conditions depending on the type of laser irradiation
- Pulsed laser irradiation:
 - H_{th} = Threshold energy density in units of J/cm²
 - E_{th} = Threshold power density in units of W/cm²
- Long pulse or CW laser irradiation
 - F_{th} = Threshold linear power density in units of W/cm
 - A pulse is considered long when the thermal transit distance, $(2D \tau_{\text{eff}})^{1/2}$, is on the order of the size of the test spot $d_{\text{T, eff}}$
 - D = Thermal diffusivity
 - In both cases, τ_{eff} = Effective pulse duration in units of s
- When a dash is present following 6/, or the 6/ is not included, the laser damage threshold is not defined and will not be tested

Wavefront Deformation from an Element or Assembly^{14, 20}

- Builds upon surface form tolerance specification where notation changes from 3/ to 13/
 - Written as 13/ A(B/C) RMSx < D; λ = E
 - Update: units of A, B, and C are waves instead of fringes
- Value specified is needs to be measurable using a single-pass metrology method, typically found to be an interferometer
- Specification would be shown on the drawing view or in a total system specification section of the table
- Assembly deformation example:
 - 13/ - RMSt < 0.04; λ = 632.8 nm
 - Example states that the measured total rms wavefront error needs to be less than 0.04 waves different from the theoretical total rms wavefront error when tested at 632.8 nm
- When a dash or nothing is listed in place of one of the tolerances, that type of tolerance will not be applied

Additional Information²⁸

- All information covered here is expanded upon in the referenced citation

Diffraction Surfaces¹⁶

- Diffraction surfaces are indicated by a # inside a circle
- Three properties of diffraction element must be specified, unless otherwise inferred from the type of grating (transmission grating for CGH)
 - Basic type of diffraction structure (e.g. LG = Linear grating)
 - Direction of diffracted light (e.g. RG = Reflection grating)
 - Type of structure (e.g. SR = Surface relief grating)
- Test region of diffraction structure needs to be shown in a face view with proper hatching to show applicable area (e.g. for a linear grating straight lines in the direction of the grating are shown)
 - Similar to effective aperture, you use ϕ_h
- Specification of type of grating is different for each basic type of diffraction structure
 - Linear grating: Diffraction parameters and direction of linear grating
 - Circular grating: Mathematical description and diffraction parameters
 - Computer generated hologram: Data set for processing and describing diffraction structure

Asphere and Freeform Surfaces^{12, 19, 29, 30}

- Both aspheric and general (freeform) surfaces are toleranced based on their surface form (as per ISO 10110-5)
 - A sagitta table with Δz (sag) and/or Δs (slope) should be included
- Aspheric surfaces are rotationally invariant about the optical axis
 - Surface type in tabular field is indicated as "ASP"
 - Surface shape is described through a multi-term equation
 - Conic section and a power series

$$z(h) = \frac{h^2}{R \left[1 + \sqrt{1 - (1 + K) \left(\frac{h}{R} \right)^2} \right]} + \sum_{i=2}^n A_i h^{2i}$$
 - Conic section and orthogonal polynomials
 - Multiple types of equations commonly referred to as Q-type surfaces
 - Coefficients and equation needed to describe the surface must listed and referred to in the surface radius designation
- General (freeform) surfaces are rotationally variant across the optical surface
 - Surface type in tabular field is indicated as "GS"
 - Surface shape is described by mathematical equation, except coordinate system is critical in determining where the surface is described about
 - For a cloud of points, the indication "GS" and the datafile name replaces the R for the surface, with a date and time stamp for the data file

Surface Treatment and Optical Coatings^{9, 22-26}

- Functional coatings are indicated by a λ inside a circle
- As defined in ISO 9211-2 descriptions and applications of an optical coating must precede the specifications for spectral characteristics (e.g. Antireflecting [AR] or Filtering [FI])
 - Coatings specifications can primarily be broken down into three designations
 - $\tau(\lambda)$ or T(λ) = transmission for a waveband
 - $\rho(\lambda)$ or R(λ) = reflectance for a waveband
 - $\alpha(\lambda)$ or A(λ) = absorptance for a waveband
 - Additional methods are possible to describe an optical coating past the waveband
 - Angle of incidence (AOI)
 - Aperture size
 - Polarization orientation
 - Phase
- Coating durability can be specified on a drawing using a test code, test sequence, and number of samples
 - List of possible test codes and sequences are in ISO 9211-3
 - Test codes are based on ISO 9022, environmental testing series, and ISO 9211-4, coating specific durability tests
- Surface treatments
 - Indicated on the optic by a thick chain line adjacent to the treated region
 - Specifications are written in a box with a leader line to the treated region
- Surface treatment applications
 - mitigate damage to the optic (e.g. handling)
 - Provide functional uses outside main use of the optic (e.g. stray light control)

General Notation^{1, 11}

- Drawings can be prepared for an optical element or subassembly
- Default conditions unless stated otherwise:
 - Temperature = 20°C
 - Dimensional Units = mm
- Each tolerance property is applied for multiple cases:
 - X/ = element tolerance
 - 1X/ = subassembly tolerance
 - 0X/ = raw material tolerance
- Fundamental dimensions for a rotationally invariant optical element
 - Radius = dimensional value preceded by an R and the curvature orientation (CX or CC)
 - Thickness = dimensional value including tolerance unless specified otherwise
 - Diameter (ϕ) = dimensional value including tolerance
 - Effective diameter (ϕ_e) = sub-aperture where optical tolerances apply
- Edge corners
 - Bevel = functional corner specified with a dimension, tolerance, and angle
 - Chamfer = nonfunctional corner specified as the maximum or minimum allowed face width
- Unless stated within each tolerance where a wavelength value is necessary, the title block must include reference wavelength
 - As of ISO 10110-1 2019 there is no default wavelength
- Values that do not have tolerances listed, or are meant to be ignored, have a default tolerance
 - Tolerances are based on the diameter of the lens

References (Full standard is required for proper use, poster for reference only)

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